## Large-Sample Inference and Frequency Properties of Bayesian Inference:

• Home Work 2 – discussion

Normal Approximations to the posterior distribution

- Joint posterior
  - Convenient to approximate a unimodal and roughly symmetric posterior density by a normal distribution, centered at the mode.
    - Log posterior approximated as a quadratic function by a Taylor Series expansion.

$$\log p(\boldsymbol{q} \mid \boldsymbol{y}) = \log p(\hat{\boldsymbol{q}} \mid \boldsymbol{y}) + \frac{1}{2} (\boldsymbol{q} - \hat{\boldsymbol{q}})^T \left[ \frac{d^2}{d\boldsymbol{q}^2} \log p(\boldsymbol{q} \mid \boldsymbol{y}) \right]_{\boldsymbol{q} = \hat{\boldsymbol{q}}} (\boldsymbol{q} - \hat{\boldsymbol{q}}) + \cdots$$

- (Mode must be in the interior of the parameter space, and assume that the derivatives exist.\_
- First order term is zero since the first derivative at the mode is zero.
- Normal distribution with Unknown mean and variance
  - Using non-informative prior on  $(m \log s)$ , expand its posterior around the mode and approximate it by a joint normal
- Interpretation of the posterior density function relative to the density at the mode
- Summarizing posterior distributions by point estimates and standard errors
  - Transformations to an appropriately defined functions of the parameters can improve the normal approximation
- Data reduction and summary statistics
  - Posterior mode and its curvature at the mode
  - If normal approximation not good, these summaries may be misleading.

- Lower dimensional normal approximations
  - For a finite sample size, the normal approximation is typically more accurate for conditional and marginals than for the full joint dist
    - Marginalizing leads to averaging over all other components of the parameter vector.
    - Bioassay Experiment
      - Approximation in the main body may be OK.
        May lose some of the tail features

(skewness, and tail approximation)

## Large-Sample Theory

- Amount of data from some fixed sampling distribution, f(y), increases
- Asymptotic normality of the posterior distribution, even if the true distribution of the data is not within the parametric family under consideration
  - Modeled likelihood p(y|q) and prior p(q)
  - If f(y) belongs to this family for some  $q_0$ , then in addition to asymptotic normality, 'consistency' also holds.
  - O If not, then the  $q_0$  is replaced by a density in the class, that is closest to the true f(y) in the Kullback Leibler distance.
  - The Fisher information J(q) is an important component of the asymptotic distribution
- Asymptotic Normality and Consistency
  - O Appendix B has the proof under some regularity conditions
  - Continuous function of the parameter and the true  $q_0$  is not on the boundary of the parameter space, twice differentiable
  - Express the second derivative at the mode in terms of the derivatives of the prior and the log-likelihood
  - As n increases the second term converges to its expectation
  - O Likelihood dominates the prior in asymptotic sense
    - So with large amount of data, eliciting prior is not that important
    - For small amount of data, prior is critical

• With no data, quality of expert knowledge is highly relevant

## **Counter Examples to the Theorems**

- Under-identified and non-identified parameters
  - Likelihood is same for many different points
    - Recognize the problem exists and get more info or put some constraints on the parameter space
- Number of parameters increasing with sample size
  - Neyman-Scott Problem
- Aliases
  - Mixture models may have two modes
- Unbounded likelihood
  - Mode does not exist
- Improper Prior distributions
  - May lead to improper posterior
- Priors that the point of convergence
- Convergence to the edge of the parameter space
- Approximation not good in the tails

Frequency evaluation of Bayesian Inference

- Large Sample correspondence leads to normal approximation
- Similar interpretation as Frequency theory inference
  - o Consistency
  - o Efficiency
  - Decision analysis
  - o Asymptotic unbiasedness
  - o Confidence coverage