



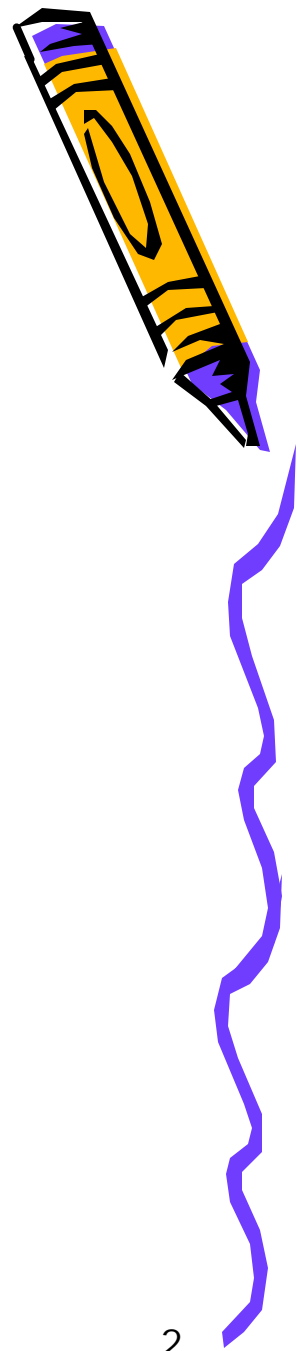
A Bayesian Approach for Spatial Analysis of Lung Cancer Rates in Ohio

Hu Wei
Department of Geography
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Disease mapping

- Definition
 - Mapping the spatial dispersion of a certain disease across the study area
- Objective
 - Infer the geographic distribution of the rates and then identify areas of higher or lower incidence.



Mapping Relative Risk

- Relative risk measures how much a particular risk factor influences the risk of a specified outcome (e.g., cancer mortality)
- Classical approach is mapping SMRs (standardized mortality/morbidity rates) for subregions based on Poisson model
- Compute P-values for SMRs to identify areas with significantly high (or low) relative risk



Poisson Model



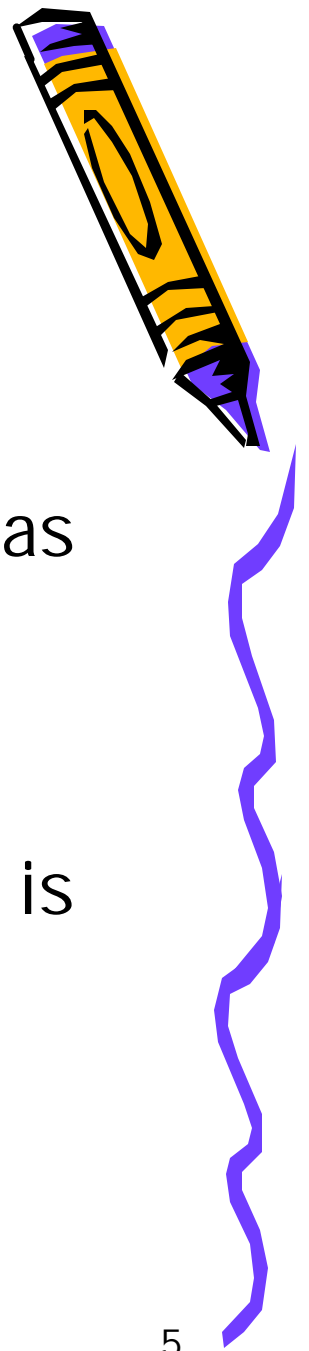
- For rare events a Poisson model is commonly adopted.

$$O_i | E_i, \mathbf{y}_i \sim \text{Poisson}(E_i \mathbf{y}_i)$$

- SMR = O_i/E_i is the MLE estimator of Relative Risk from the Poisson model, with estimated standard error $s_i = \sqrt{O_i}/E_i$ asymptotically.
- P-value can then be computed for each area with a certain SMR



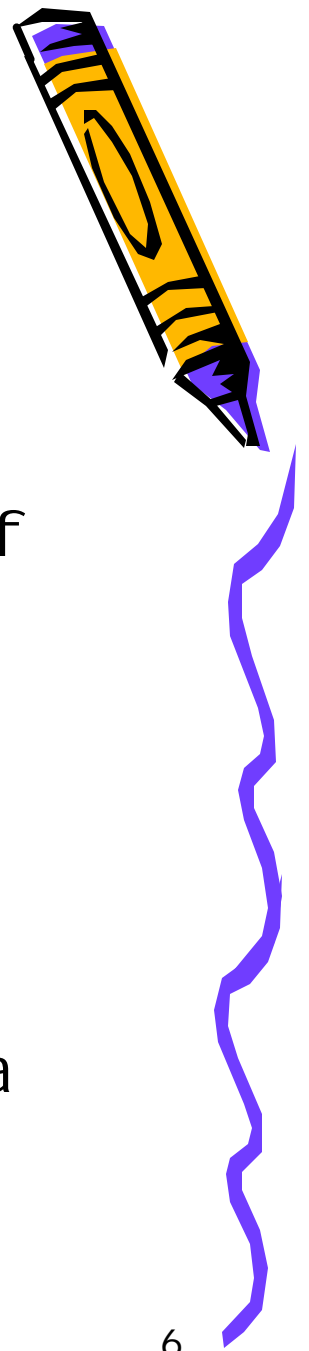
Problems of SMR



- More extreme values of the estimates may be based on a few cases only in areas with small population.
- Rare events in small areas can lead to extra-Poisson variation.
- Spatial correlation in the Relative risks is not taken into account.



Bayesian approach



- Hierarchical model
 - Enable us to incorporate multiple sources of data and knowledge (e.g., spatial autocorrelation)
- Prior specification
 - Nonspatial random effect to describe unstructured heterogeneity.
 - Spatial random effect can be expressed via Markov random fields models (CAR, Exp)

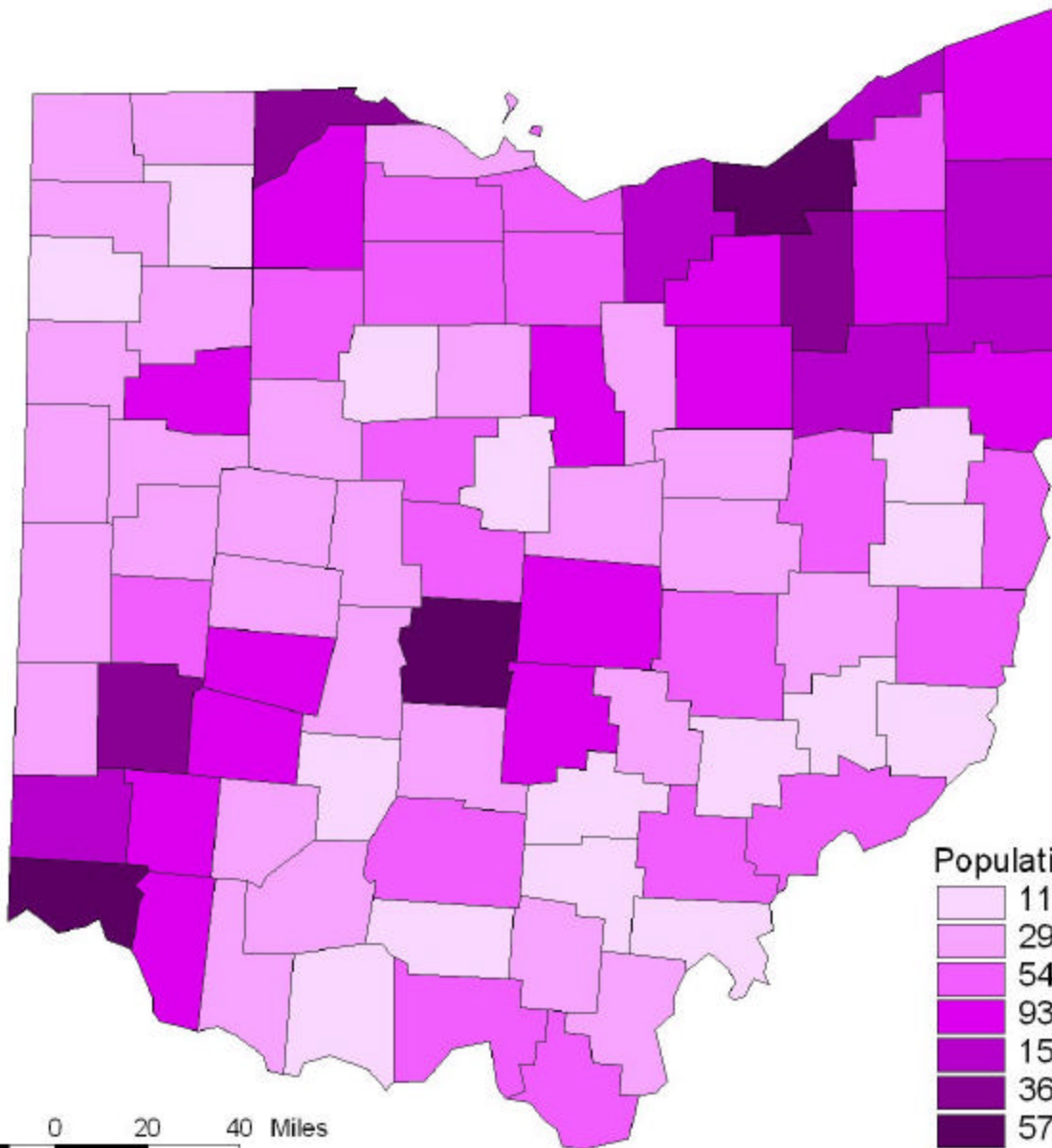
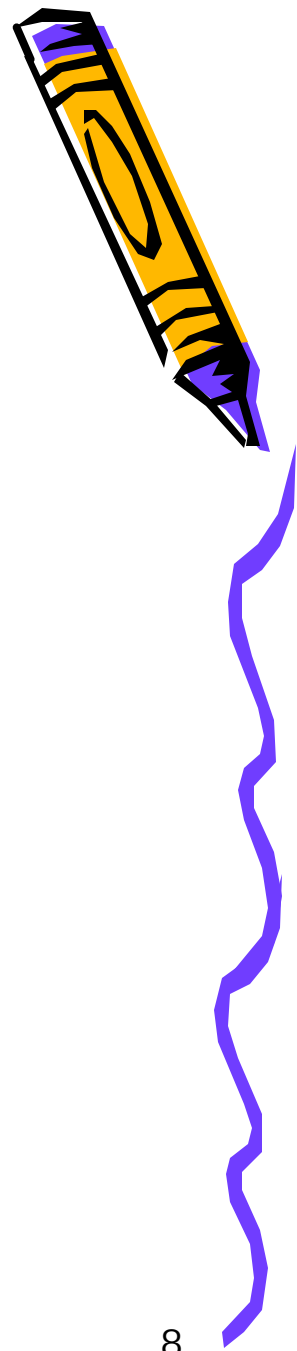


Data

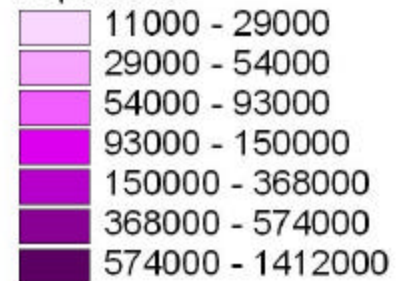
- County map and census population for Ohio
- Observed lung cancer mortality at county level
 - National Cancer Institute
- Expected lung cancer mortality
 - Population in a county multiplied by crude rate
- Covariate variables
 - Air quality data from EPA
 - Poverty level: Census
- Software:
 - ArcView GIS, WinBUGS (GeoBUGS), and R.




Population Distribution



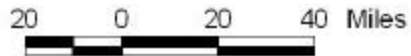
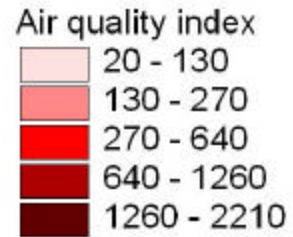
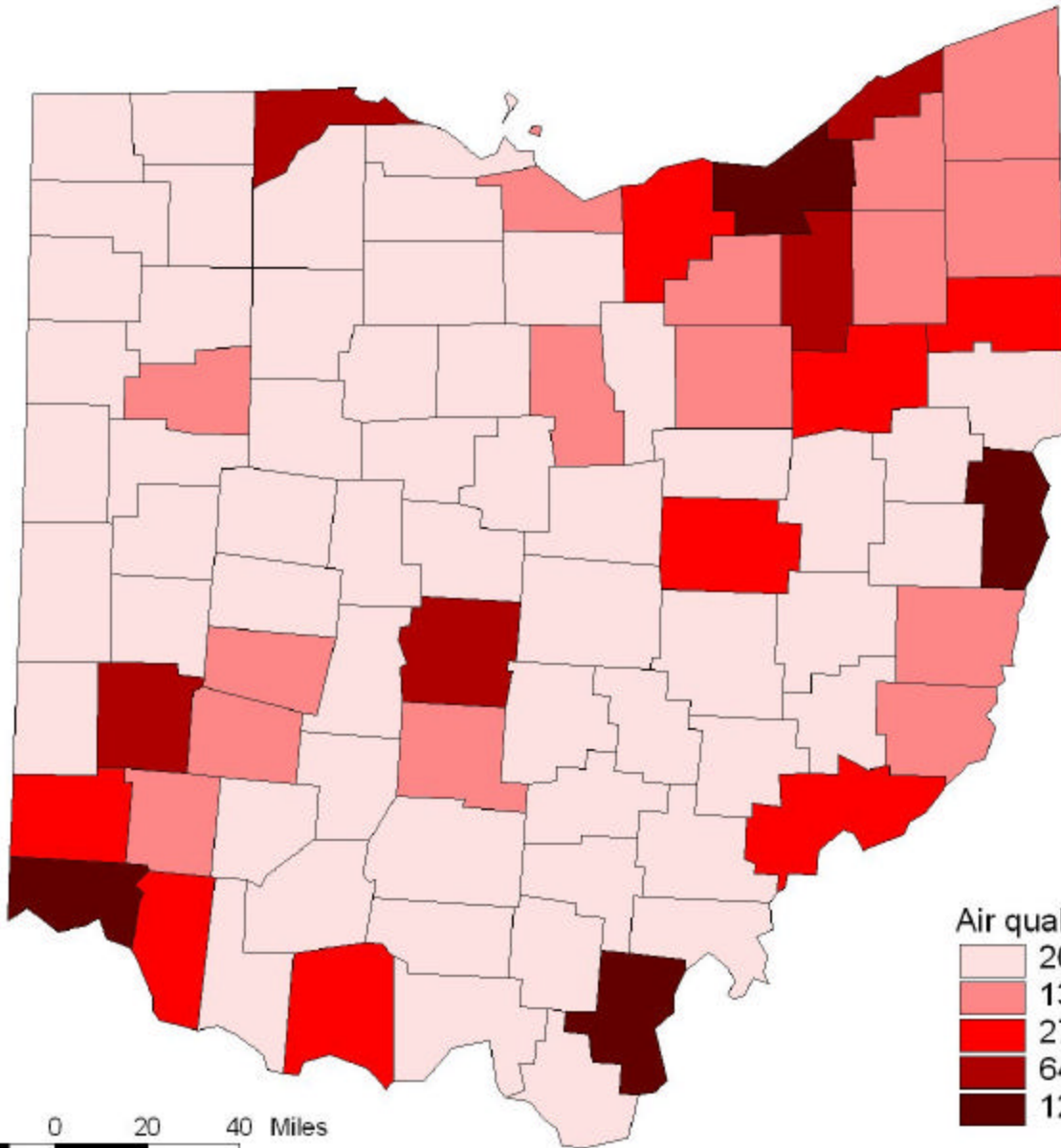
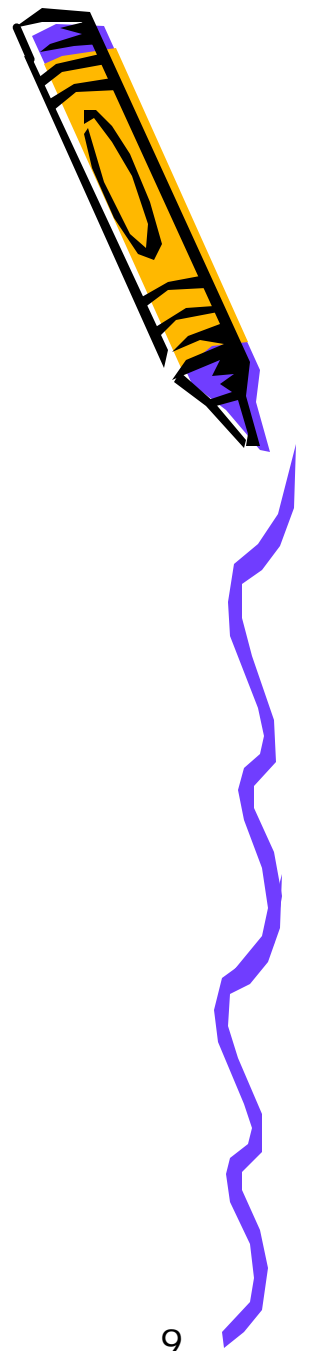
Population



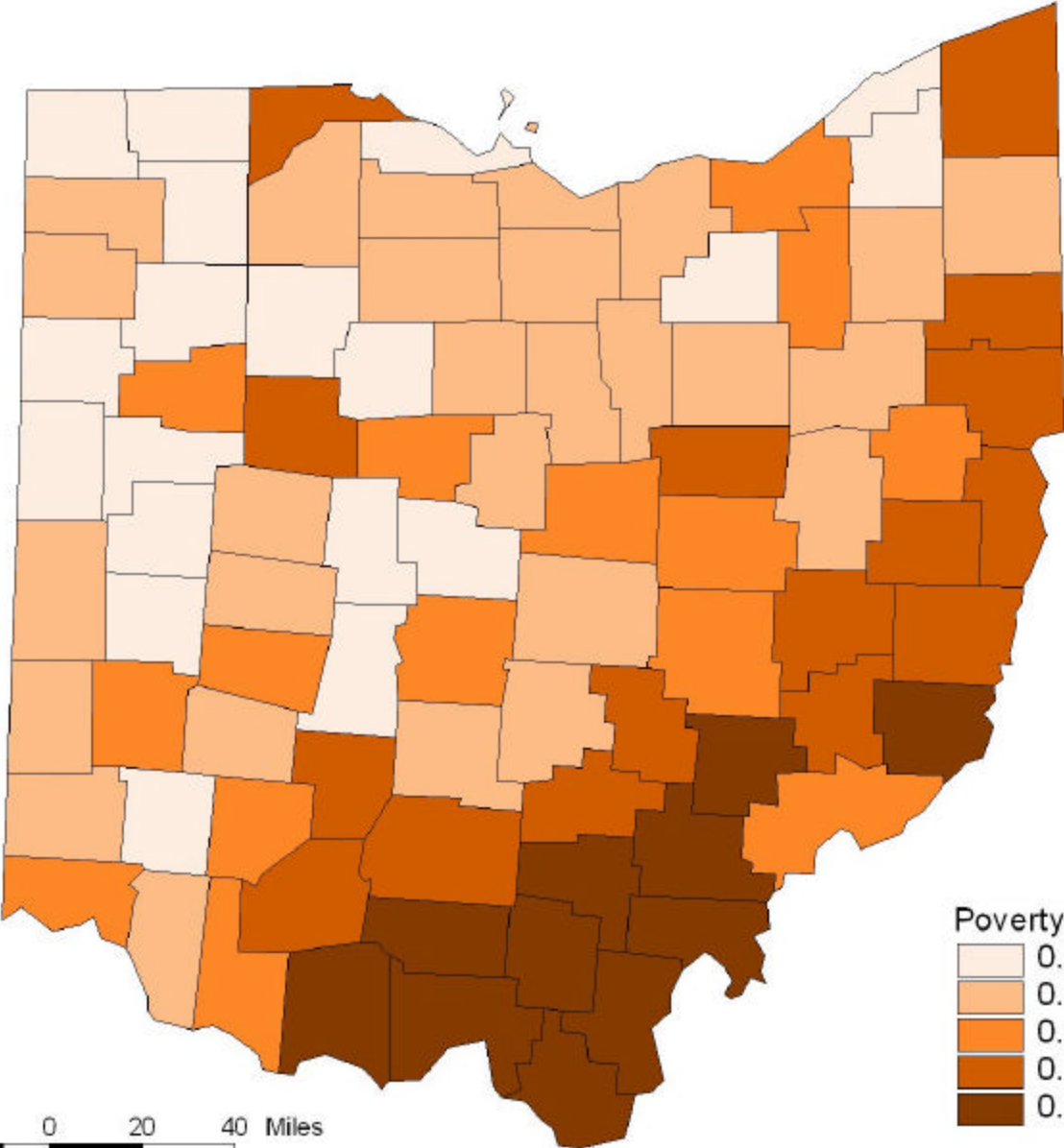
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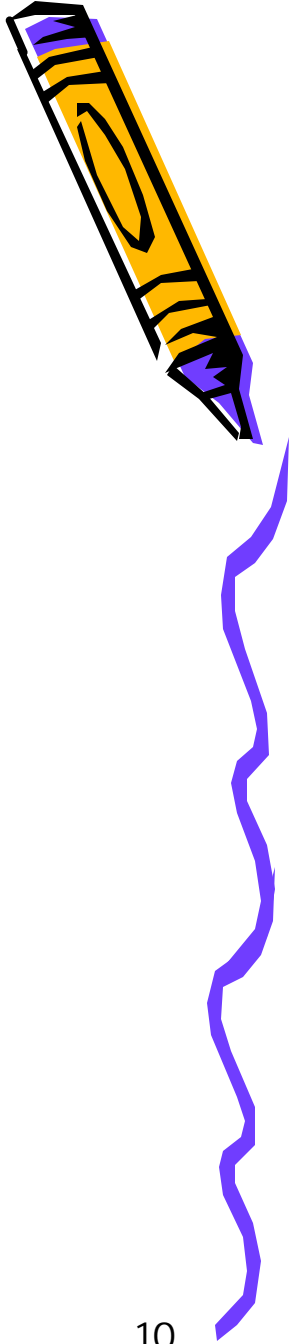
Air quality index



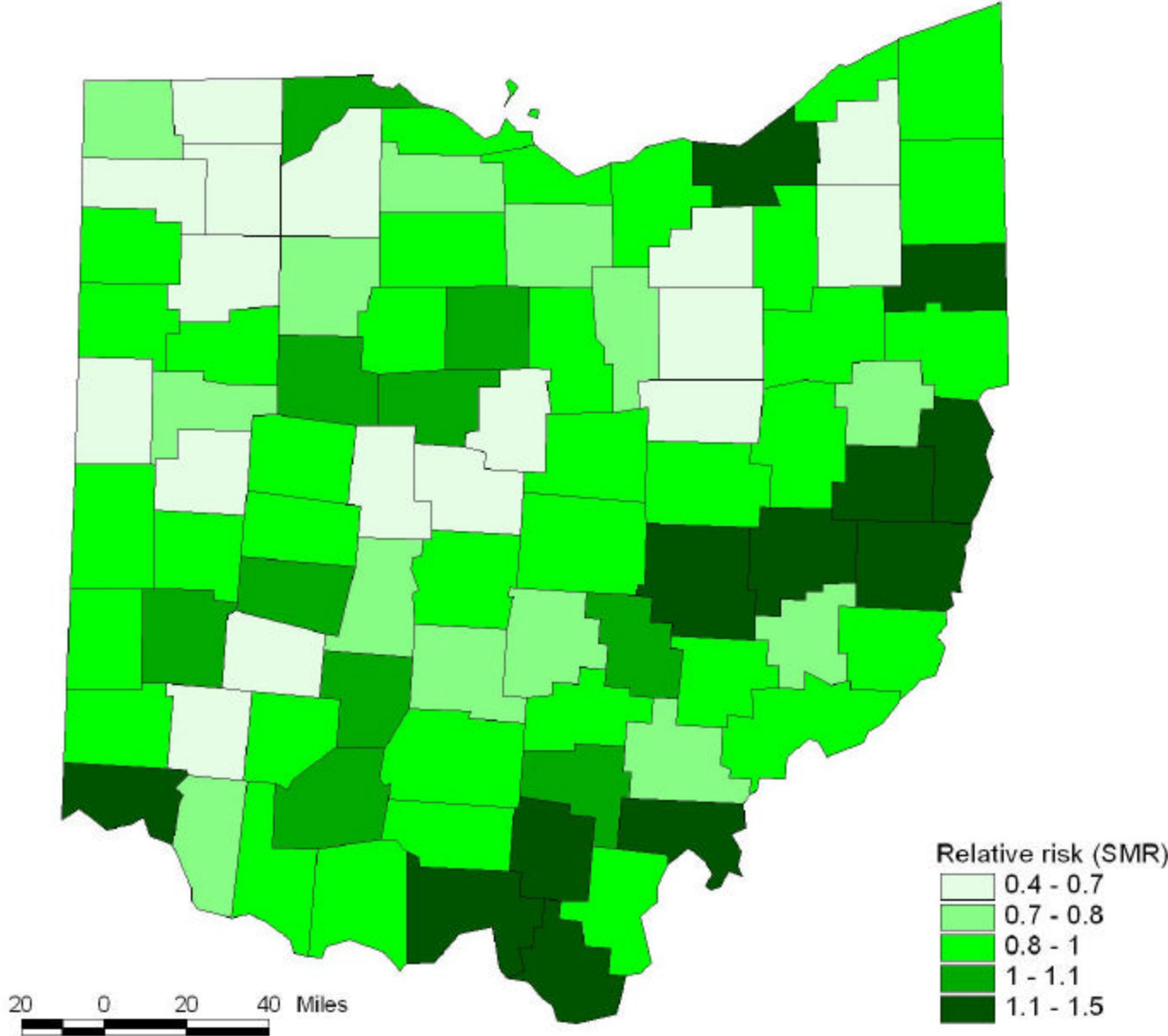
Poverty percentage



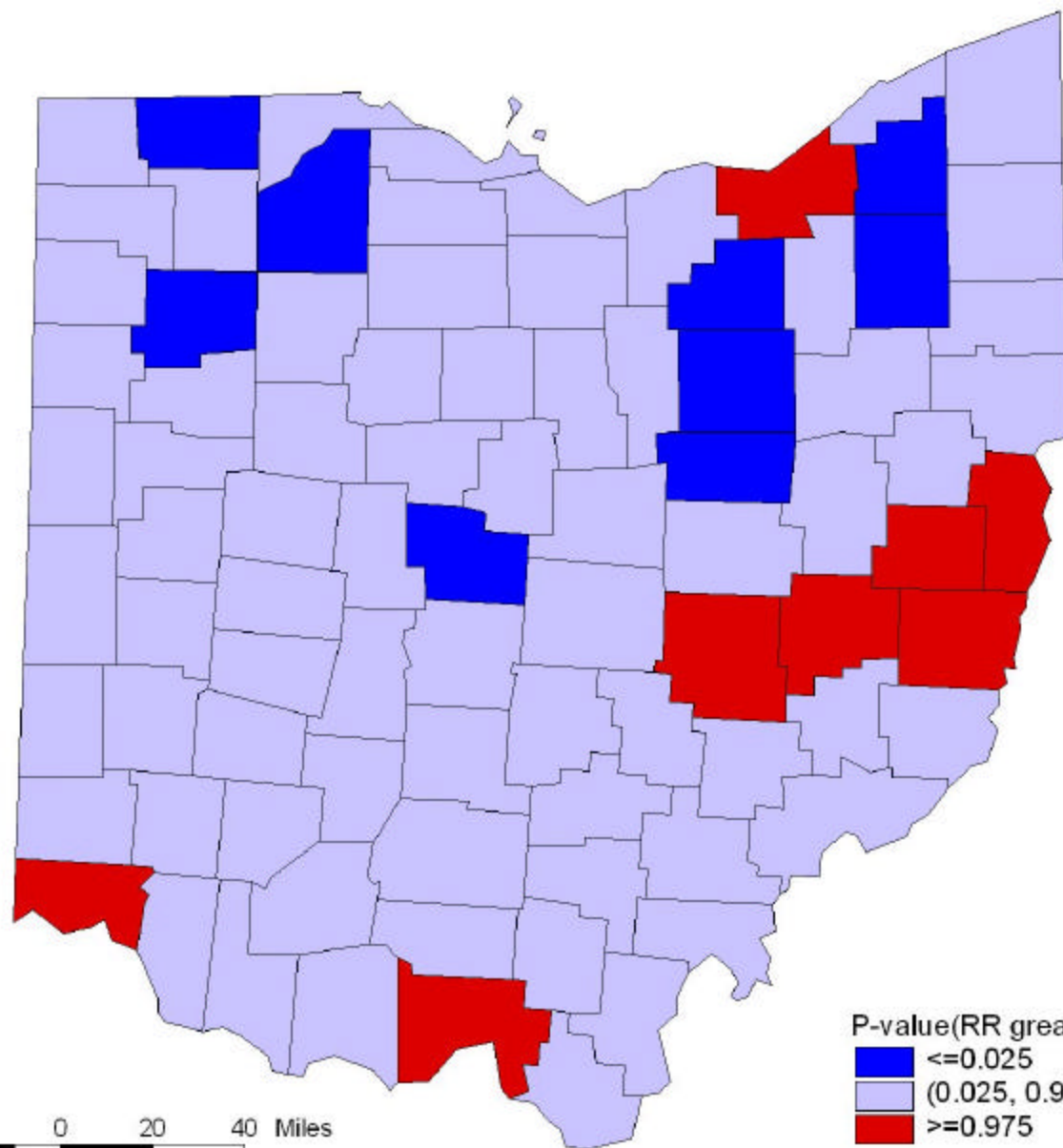
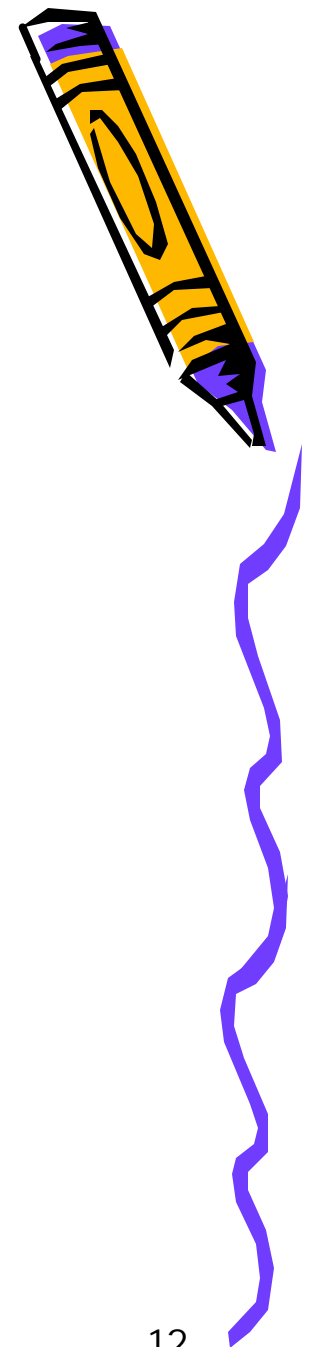
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Standard mortality rate (SMR)

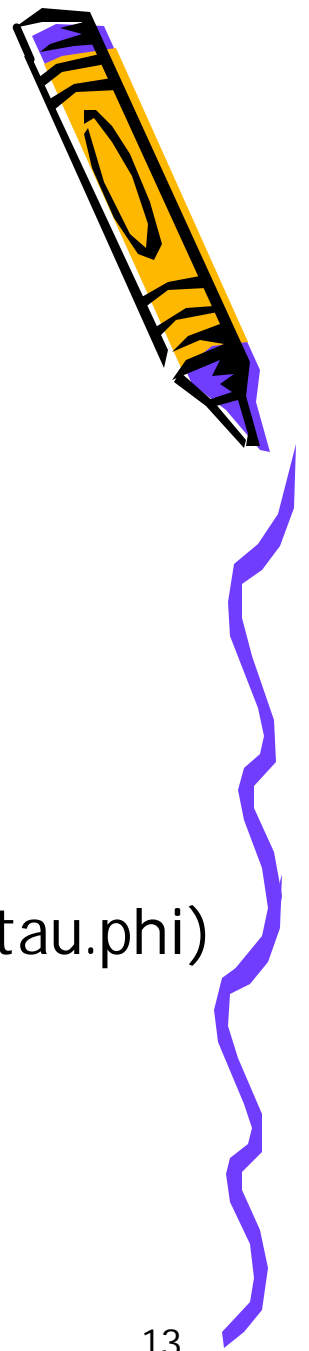


P-value



P-value(RR greater than 1)
■ ≤ 0.025
■ $(0.025, 0.975)$
■ ≥ 0.975

Hierarchical Bayesian Model using CAR prior



Likelihood:

$$O[i] \sim \text{Poisson}(\mu[i])$$

First stage:

$$\text{Log}(\mu[i]) = \text{Log}(E[i]) + \text{phi}[i] + \text{theta}[i]$$

$$\text{RR}[i] = \exp(\text{phi}[i])$$

Second stage:

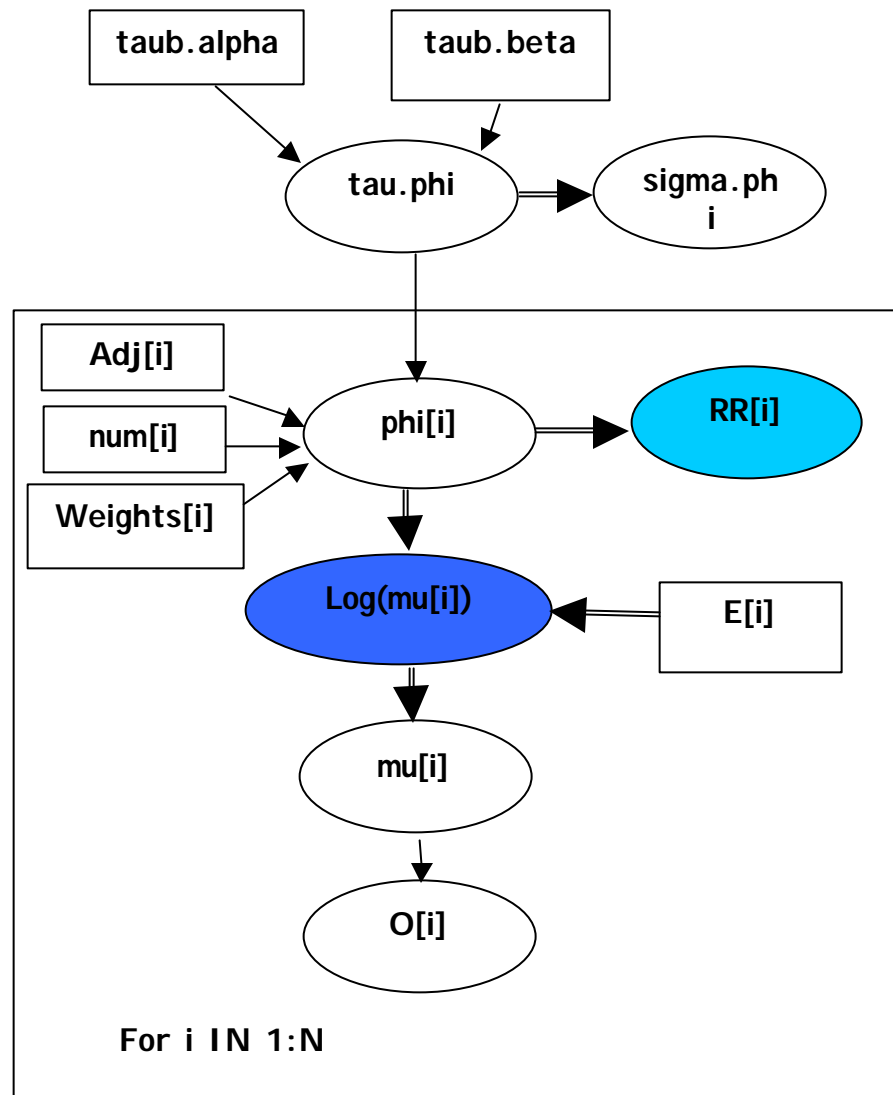
$$\text{phi}[1:N] \sim \text{car.normal}(\text{adj}[], \text{weights}[], \text{num}[], \text{tau.phi})$$

Priors:

$$\text{tau.phi} \sim \text{Gamma}(\text{taub.alpha}, \text{taub.beta})$$



Model diagram



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Example of Source Code

```
model {
  # Likelihood
  for (i in 1 : N) {
    obs.m[i] ~ dpois(mu[i])
    theta[i] ~ dnorm(0, tau.theta)
    log(mu[i]) <- log(e.m[i]) + beta0 + beta1*log.emis[i] + phi[i] + theta[i]
    RR[i] <- exp(beta0 + beta1*pov[i] + phi[i] + theta[i])
  }
  # CAR prior distribution for relative risk:
  phi[1:N] ~ car.normal(adj[], weights[], num[], tau.phi)
  for(k in 1:sumNumNeigh) { weights[k] <- 1}
  # Other priors:
  beta0 ~ dflat()
  beta1 ~ dnorm(0.0, 1.0E-5)
  #beta2 ~ dnorm(0.0, 1.0E-5)
  tau.phi ~ dgamma(0.5, 0.0005)
  tau.theta ~ dgamma(0.5, 0.0005)
  sigma.phi <- sqrt(1 / tau.phi)
}
```



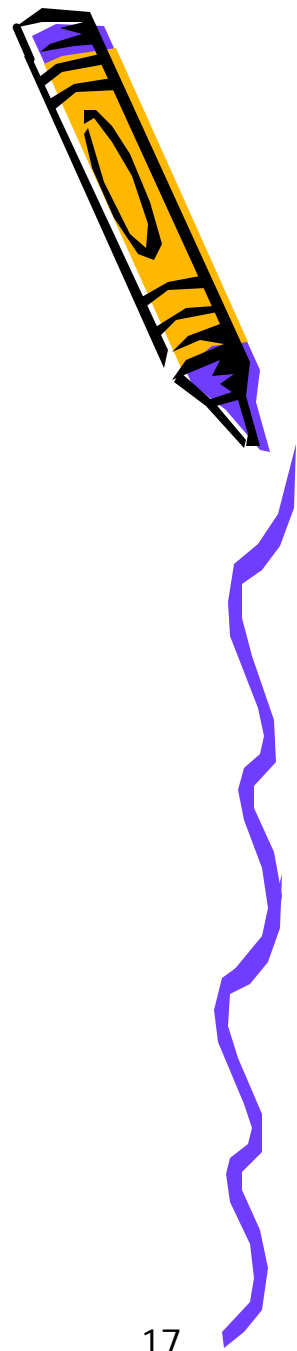
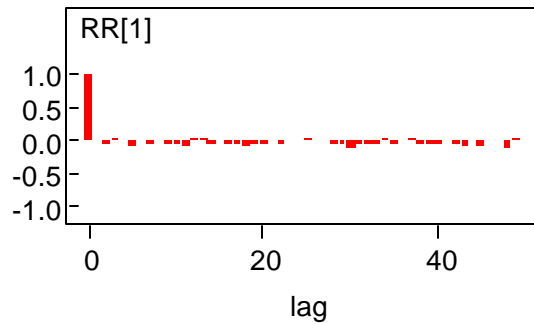
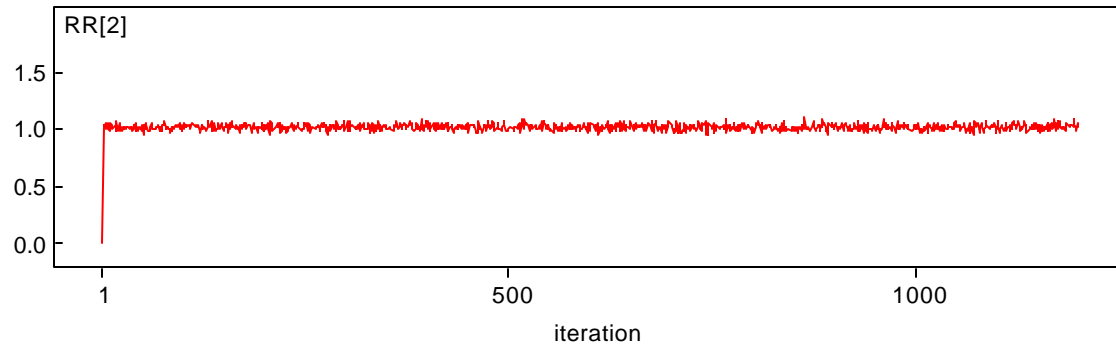
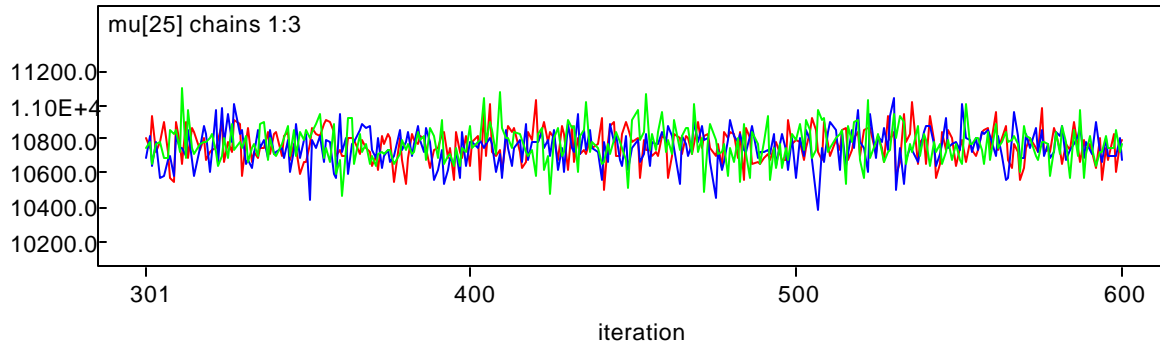
Model selection



Model		DIC	pD
No spatial structured variance		922.3	87.7
Structured & unstructured	CAR	926.5	93.5
	EXP	916.3	83.4
1 covariate log.emis	CAR	923.6	89.7
	EXP	916.7	83.3
1 covariate pov	CAR	924.3	90.6
	EXP	916.2	82.9
2 covariates log.emis and pov	CAR	921.7	88.5
	EXP	917.4	84.5

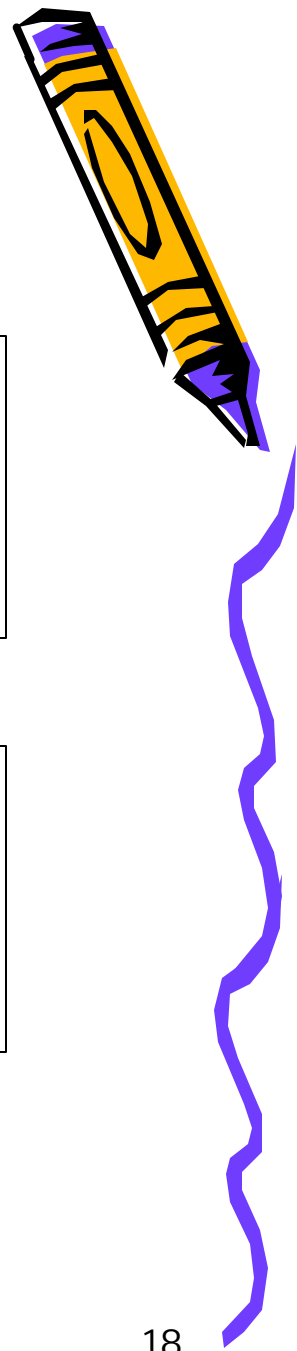
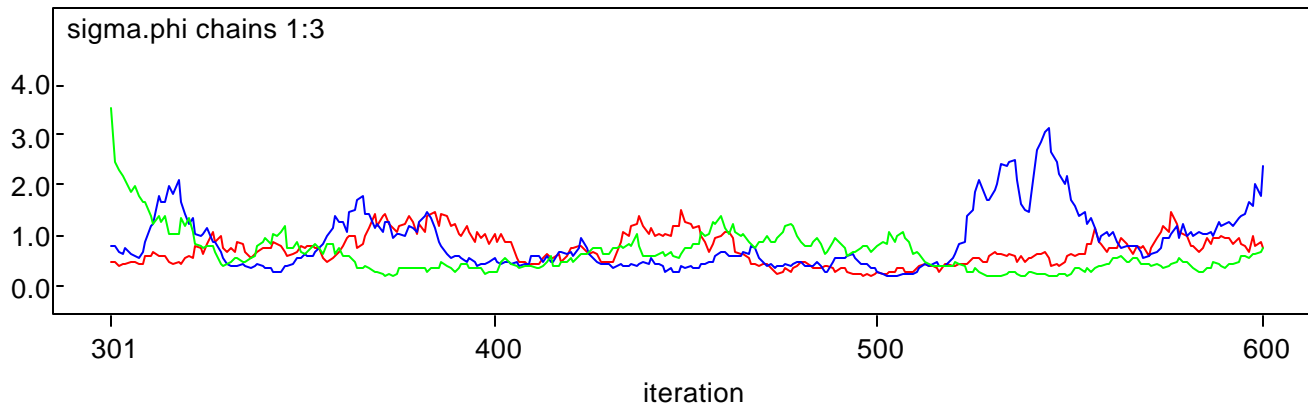
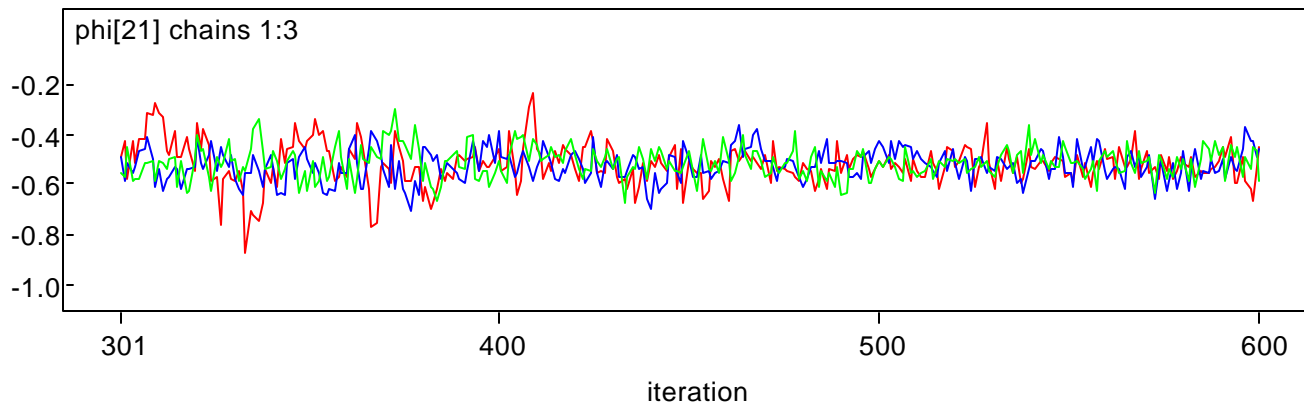


History graphs



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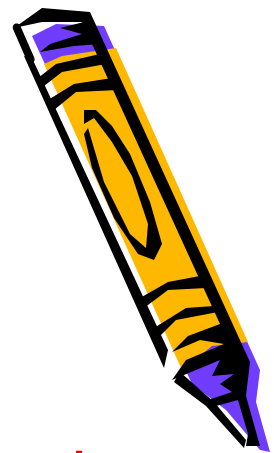
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Statistical results

One covariate (pov) with spatial structured variance

sigma.phi	210.8	56.5	120.3	141.5	234.4	254.6	286.8	7.0	3
deviance	833.3	12.9	809.8	824.7	832.6	841.9	859.4	1.0	900

pD = 82.9 and DIC = 916.2 (using the rule, pD = var(deviance)/2)

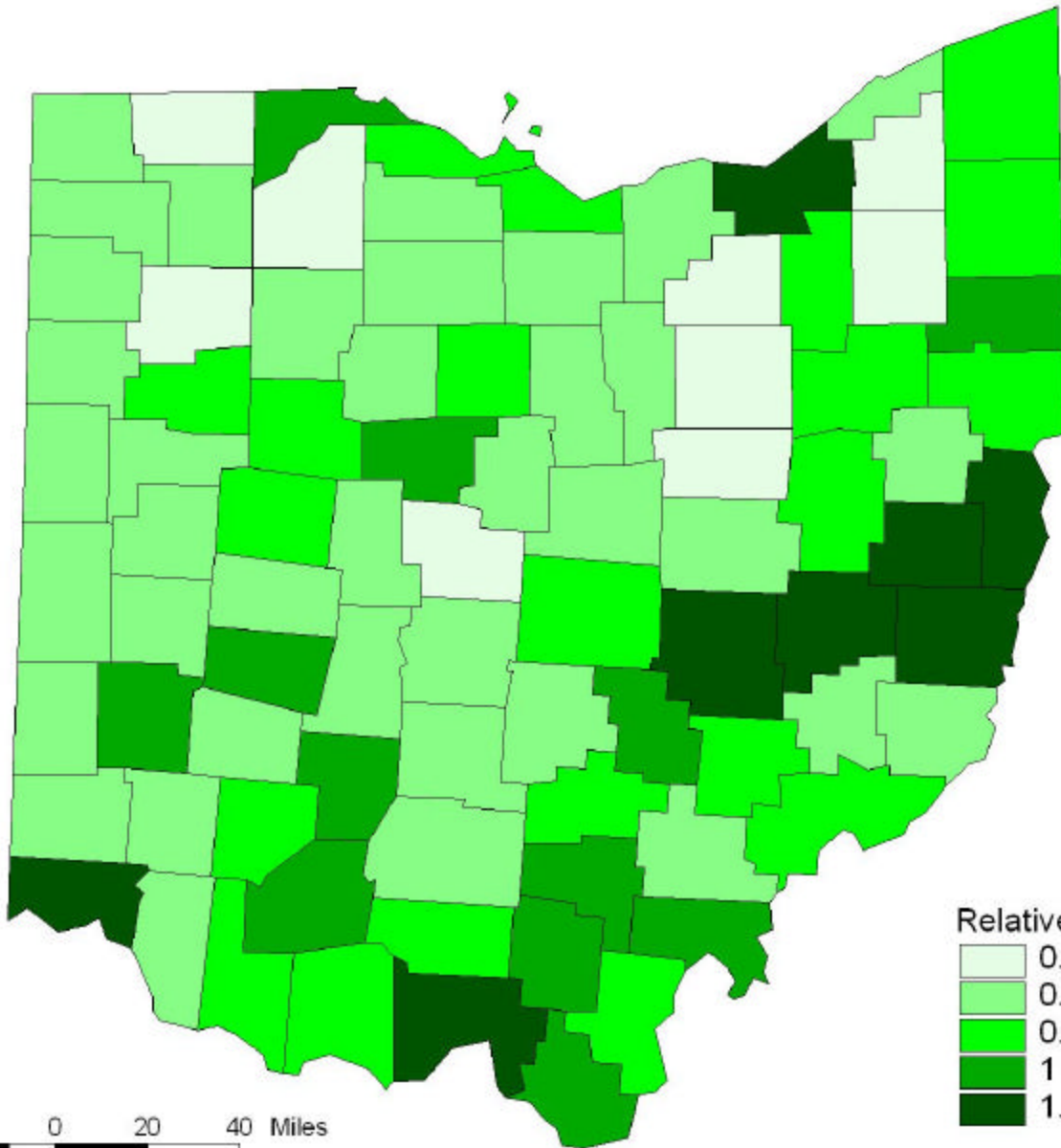
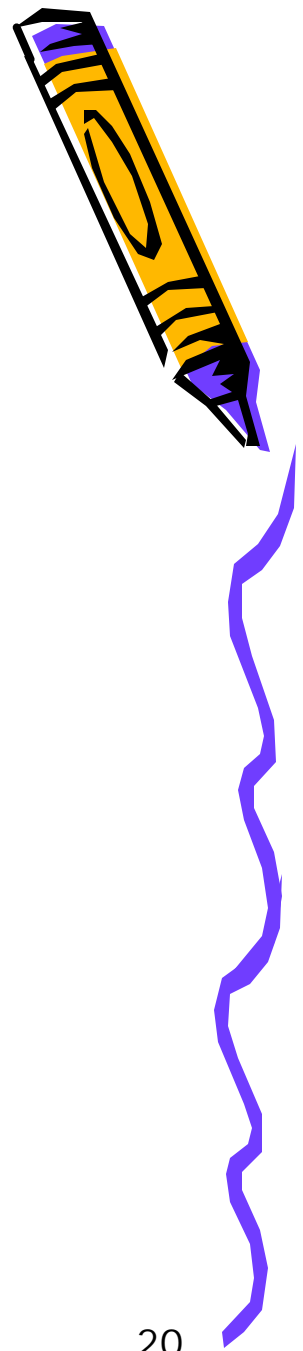


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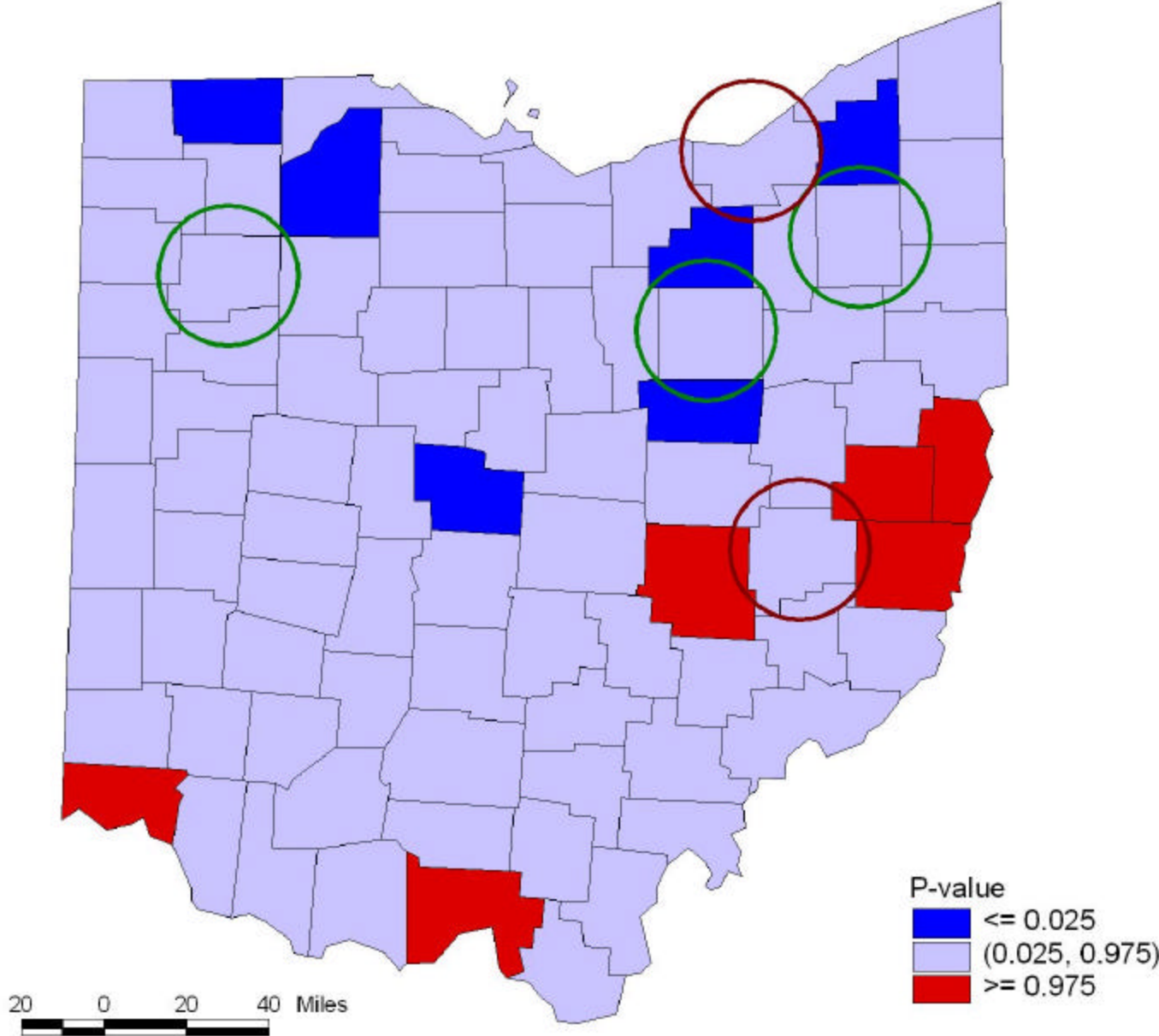
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Relative risks



20 0 20 40 Miles

P-value of RR>1



Discussion and Conclusions

- Bayesian approach helps create more interpretable map by:
 - Applying priors
 - Incorporate covariates
- p-value map identify several potential hotspots.
- Age and race adjusted rates may be used to compute expected number of cases.
- Space and time

